

Cognitive Telescope Network

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Shane Larson, PhD

Multi-messenger Astronomy
Telescopic follow-up of transient events



IBM Cloud University 2017



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Arunava (Ron) Majumdar is an integration architect with more than 16 years of experience in middleware and messaging technologies. He leads the Asset Portfolio Strategy for the IBM Cognitive Cloud and leads the Chicago Center for Advanced Studies. He has been involved with large scale design, architecture and implementation for IBM clients, helping them successfully through the project lifecycle. He has architected High Availability and Disaster Recovery solutions with IBM integration products and worked on performance testing and securing client environments. He is currently working on API Economy, Hybrid Integration, Micro-services and Pattern-based automation. Ron has several patents and published assets to his credit and is collaborating with Research faculty and Universities on innovative ideas and their implementations with emerging technologies.



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Northwestern University



@sciencejedi



writescience.wordpress.com

Shane L. Larson is a research associate professor of physics at Northwestern University, and an astronomer at the Adler Planetarium in Chicago. He works in the field of gravitational wave astrophysics, specializing in studies of compact stars, binaries, and the galaxy. He works in gravitational wave astronomy with both the ground-based LIGO project, and the future space-based detector LISA.

Shane grew up in eastern Oregon, and was an undergraduate at Oregon State University where he received his B.S. in Physics in 1991. He received a Ph.D. in theoretical physics (1999) from Montana State University. He is an award winning teacher, and a Fellow of the American Physical Society. He currently lives in the Chicago area with his wife, daughter and cats. He contributes regularly to a public science blog at writescience.wordpress.com, and tweets with the handle @sciencejedi.

- **History behind Gravitational Waves**
- **Science behind the Cognitive Telescope Network**
- **Multi-messenger Astronomy**
- **Design Thinking and Use Cases**
- **Realization of the Idea with Bluemix and Watson Services**
- **Current project collaborations**
- **Future of the Cognitive Telescope Network**

Part I: Concept to Ideation

Part II: Architecting a solution

“Only those who will risk going too far can possibly find out how far one can go.”
— T.S. Eliot

Cognitive Telescope Network

From a 100-year old Concept to Ideation

1915: Einstein publishes his paper on **General Relativity**, a geometric theory of gravitation. It generalizes **Special Relativity and Newton's Law** of universal gravitation, describing gravity as the curvature of spacetime in his **field equations**:

$$R_{\mu\nu} - \frac{1}{2}R g_{\mu\nu} + \Lambda g_{\mu\nu} = \frac{8\pi G}{c^4} T_{\mu\nu}$$

where $R_{\mu\nu}$ is the Ricci curvature tensor, R is the scalar curvature, $g_{\mu\nu}$ is the metric tensor, Λ is the cosmological constant, G is Newton's gravitational constant, c is the speed of light in vacuum, and $T_{\mu\nu}$ is the stress-energy tensor

1918: Einstein published the paper **Über Gravitationswellen**, effect of gravitational waves was calculated resulting in the **quadrupole formula** describes rate at which gravitational waves are emitted from a system of masses based on the change of the (mass) quadrupole moment. The formula reads

$$\bar{h}_{ij}(t, \mathbf{r}) = \frac{2G}{c^4 r} \ddot{I}_{ij}(t - \mathbf{r}/c),$$

where \bar{h}_{ij} is the (spatial part of) the trace reversed perturbation of the metric (i.e. the gravitational wave) and I_{ij} is the mass quadrupole moment

1936: Einstein, Rosen came to the conclusion, that **gravitational waves do not exist!**

1938: Einstein, Infeld and Hoffmann (EIH) equations show that there is **no radiation up to the order $(v/c)^4$** , the energy remains constant.

1947: Ning Hu demonstrates that **quadrupole formula occurs at $(v/c)^5$** .

1975: Hulse and Taylor discovers the **binary pulsar PSR1913 + 16**. Their data showed a **decrease of the period of revolution – as predicted by the quadrupole formula**.

2016: **Laser Interferometer Gravitational-Wave Observatory (LIGO)** team announces they had detected Gravitational Waves for the first time. The event occurred at **September 14, 2015 at 5:51 a.m. Eastern Daylight Time** (9:51 a.m. UTC) by both detectors, located in **Livingston, Louisiana, and Hanford, Washington, USA**.



Ever since the dawn of time human beings are trying to decipher the mysteries of the Universe by looking at the Sky.

~200 BC – **Hipparchus** creates a magnitude system (1-6) and catalogs 850 stars

1610 – **Galileo Galilei** publishes **Sidereus Nuncius** from his observations from the telescope

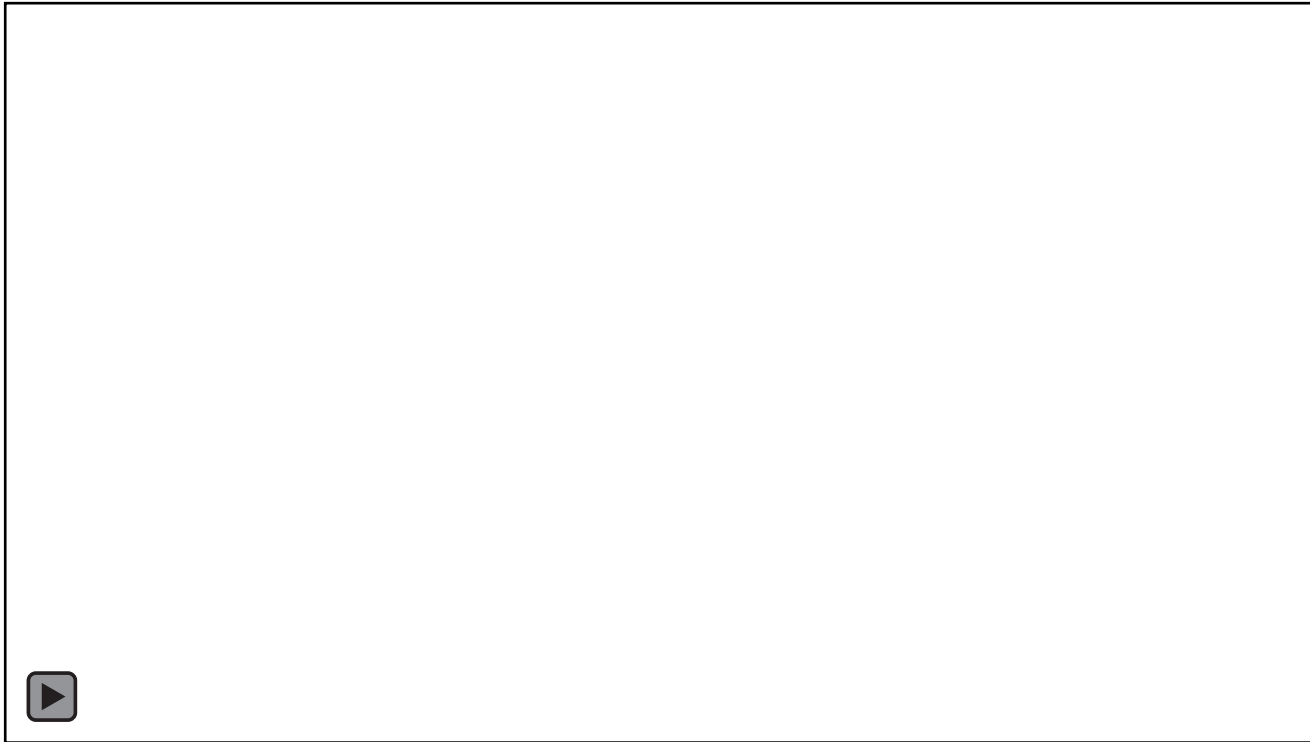
1668 – **Isaac Newton** builds reflecting telescope

1990 – **Hubble Space Telescope** is launched by **NASA**

2009 – Largest Telescope on Earth commissioned **Gran Telescopio Canarias**, **Canary Islands, Spain** beating Keck 1 and Keck 2, Mauna Kea Observatory, Hawaii

2012 – Construction of **Giant Magellan Telescope** will be located at Cerro Las Campanas at Las Campanas Observatory in the **Atacama Desert of Chile**

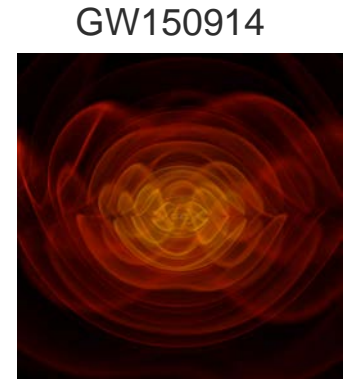
2018 – **James Webb Space Telescope** expected to be launched



Since the prediction by Einstein scientists have been trying to detect Gravitational Waves.

- Detect not with light, but with gravity.
- Gravitational waves are complementary to photons
 - Photons are made by atoms
 - Gravitational waves made by the dynamic motion of matter
- Laser Interferometers, not telescopes are required for the detection
- **LIGO** – US-based detectors at *Livingston*, Louisiana, and *Hanford*, Washington
- **VIRGO** – Italy-France-based initiative at Santo Stefano a Macerata, Cascina , Italy
- **LISA** – 1st Space-based Interferometer using 3 satellites, European collaboration

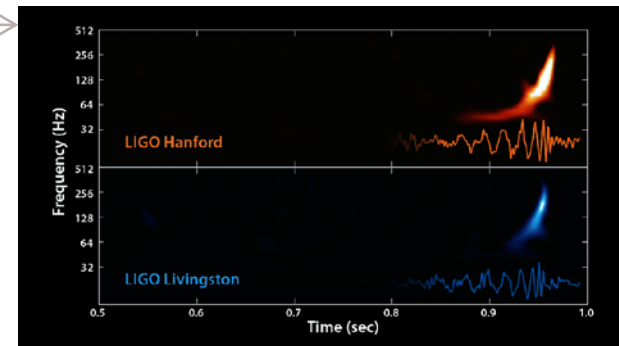
Courtesy: Simulating eXtreme Spacetime (SXS) Project: www.black-holes.org



29 solar mass black hole +
36 solar mass black hole
1.3 billion lightyears away
(400 Mega parsec)

- (1995) TAMA 300 - Japan - Decommissioned
- (1995) GEO 600 - Sarstedt, Ruthe, Germany: <http://www.geo600.org/>
- (2002) **LIGO** - Livingston, Louisiana and Hanford, Washington, USA: <http://www.ligo.org/>
- (2003) MiniGrail - Leiden University, Netherlands: <http://www.minigrail.nl/>
- (2005) Pulsar Timing Array (using radio-telescope): https://en.wikipedia.org/wiki/Pulsar_timing_array
 - Parkes PTA, European PTA, North American Nanohertz Observatory for Gravitational Waves (NANOGrav)
- (2006) CLIO - prototype for KAGRA
- (2007) **Virgo** - Santo Stefano a Macerata, Cascina, Italy: <https://www.ego-gw.it/>
- (2015) LISA Pathfinder, a development mission for LISA, launched in Dec. - switched off 18 July, 2017
- (2018) KAGRA - Gifu Prefecture, Japan: <http://gwcenter.icrr.u-tokyo.ac.jp/en/>
- (2023) IndIGO - (Hingoli, Maharashtra?), India: <http://www.gw-indigo.org/tiki-index.php>
- (2025) TianQin - Sun Yat-sen University, Zhuhai campus, China [Space-based]
- (2027) DECIGO - Japan [Space-based]
- (2034) **LISA** - Denmark, France, Germany, Italy, The Netherlands, Spain, Switzerland and the UK
 - supported US, [Space-based]: <https://www.lisamission.org/>
- (2030s) Einstein Telescope - European Union: <http://www.et-gw.eu/>

C. Messenger (Glasgow) & LIGO

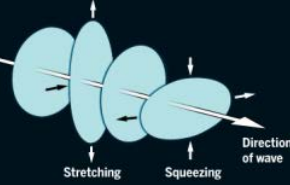


Catching a wave

As Einstein calculated, a whirling barbell-shaped mass, such as two black holes spiraling together, radiates ripples in space-time: gravitational waves.



Zooming along at light speed, a wave stretches space in one direction and squeezes in the perpendicular direction, then reverses the distortions.



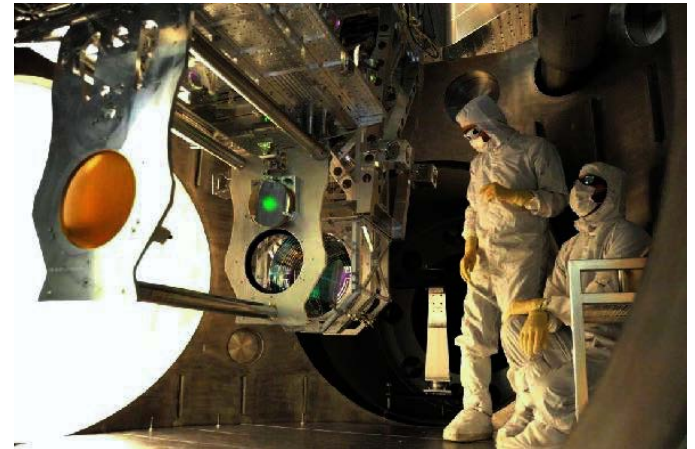
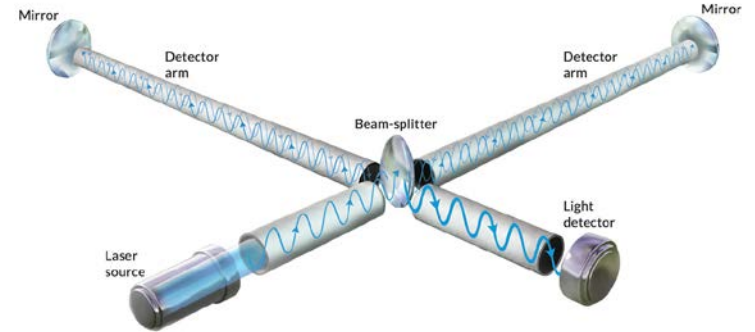
LIGO has detected waves of wavelength roughly equal to the distance between the detectors. The waves stretch each detector by about 1/10,000 the width of a proton.



Earth

4 km arms house two laser beams

Light bounces back and forth in the 4-kilometer arms of a LIGO interferometer. When a wave makes the arms unequal in length, light leaks out the interferometer's "dark port," revealing the wave.



Sound of Gravitational Waves: <https://www.ligo.caltech.edu/video/ligo20160211v2>

GW150914

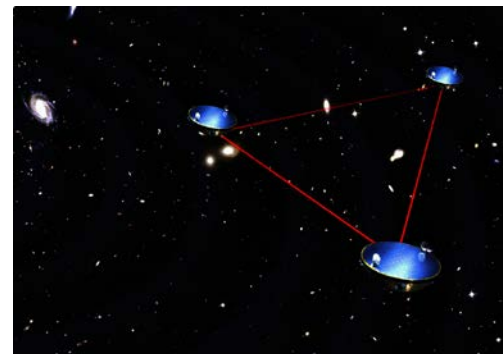
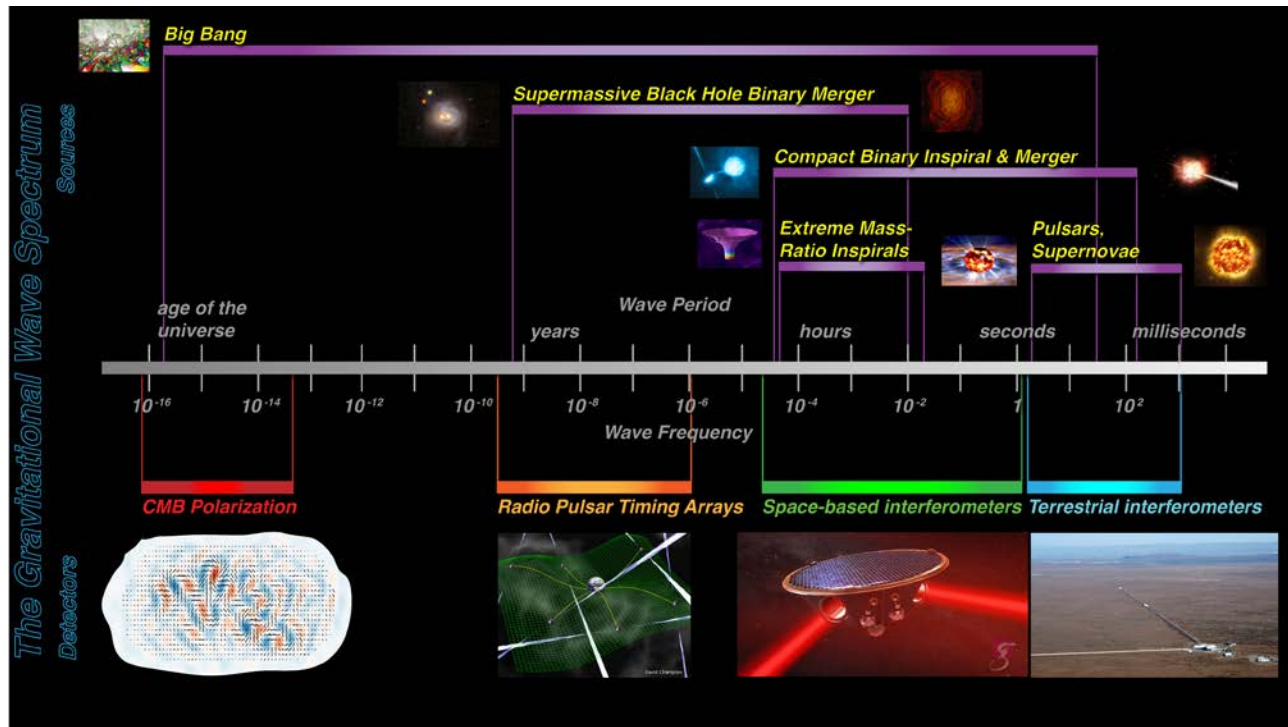
29 + 36 solar mass black hole merger resulted in 62 solar mass black hole.

GW151226

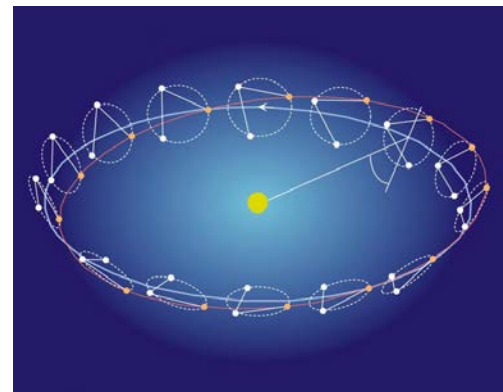
14 + 8 solar mass black hole merger

GW170104

31 + 19 solar mass black hole merger

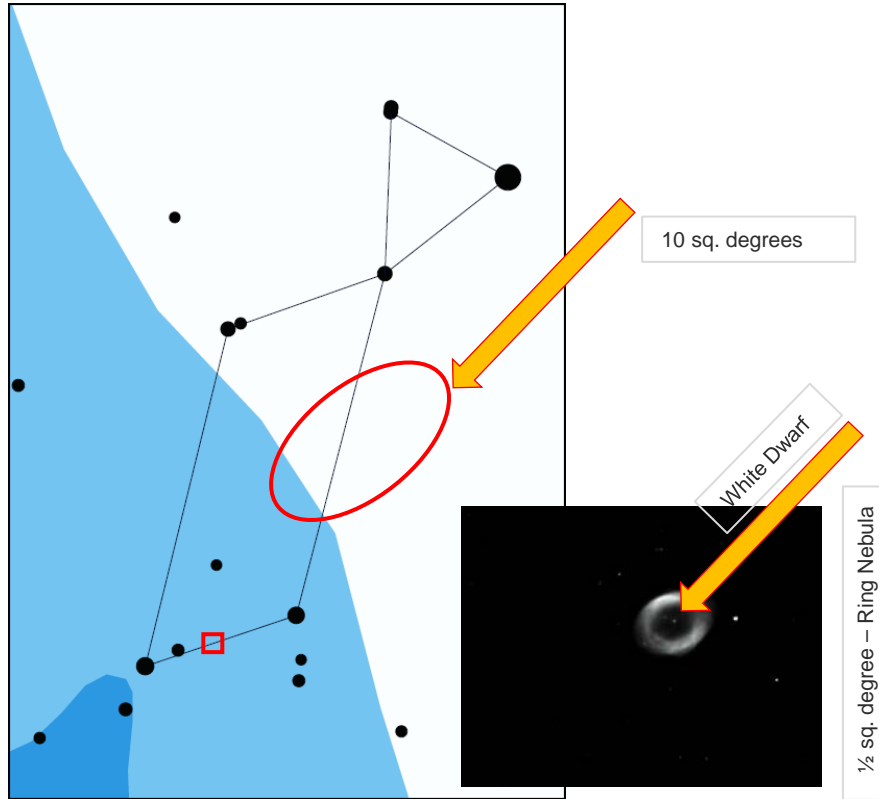


LISA: 5 million km arms



Set of three orbits in a near-equilateral triangular formation for thermal stability

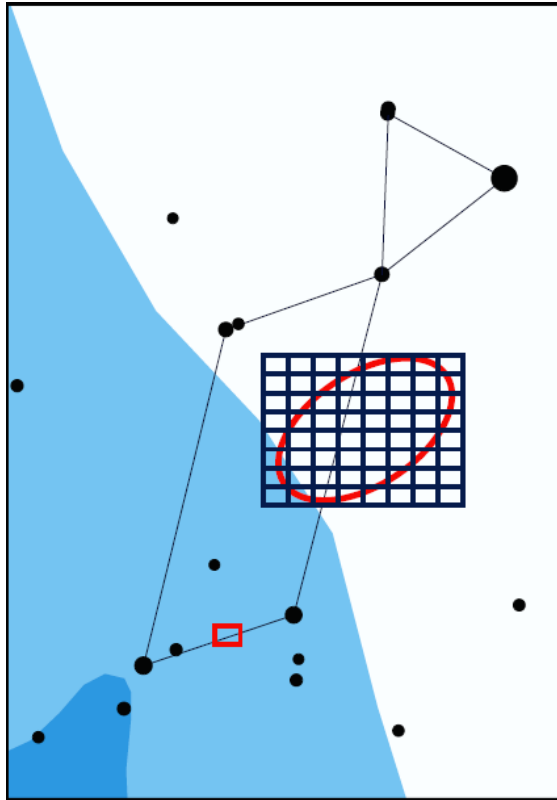
Gravitational wave detectors required for different frequencies: NASA/J. I.Thorpe:
https://imagine.gsfc.nasa.gov/features/satellites/archive/lisa_exhibit.html



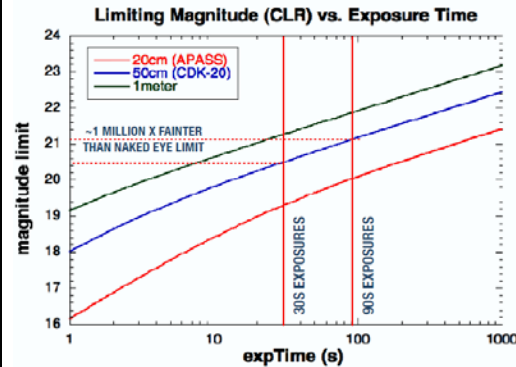
Lyra constellation and comparing areas in the sky

Challenges

- GW detectors are poor at pointing, ~ 1 to 10 sq. degrees
- Standard telescopes cover small areas, ~ 1/2 sq. degree
- **LIGO STRATEGY:** Statistically point, look for galaxies in the oval
 - *Cannot work when there are 1000's of galaxies in the region*
- **LISA STRATEGY:** All sky surveys, cooperate wide field scopes (e.g. Large Synoptic Survey Telescope (LSST))
 - *Not a strong taxonomy of transient sky phenomena for rejection*
 - *Hard to determine what's a gravitational wave and what's changing magnitude for something else*

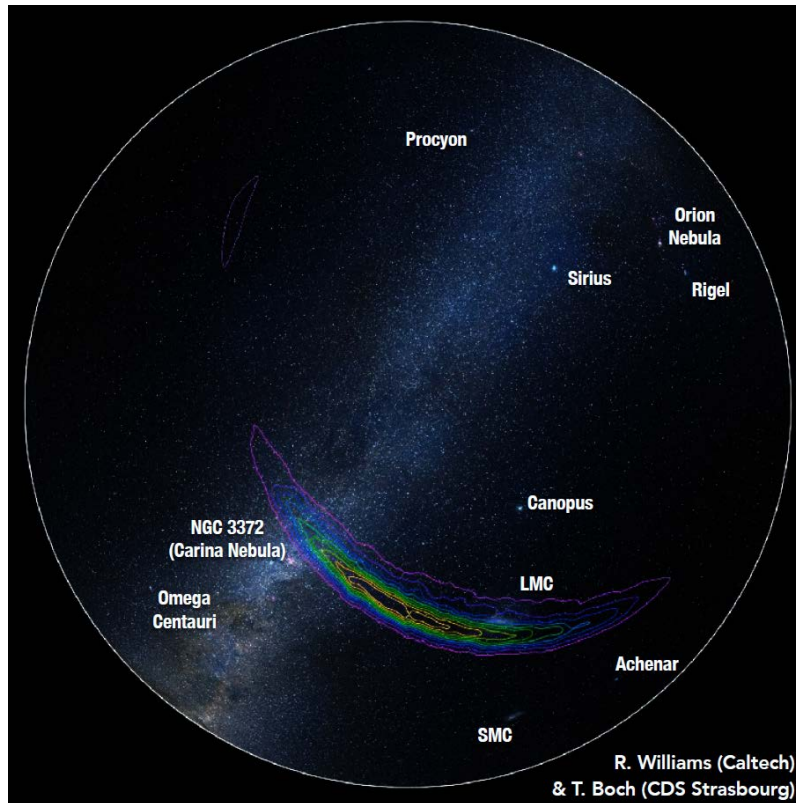


Lyra constellation tiling the oval

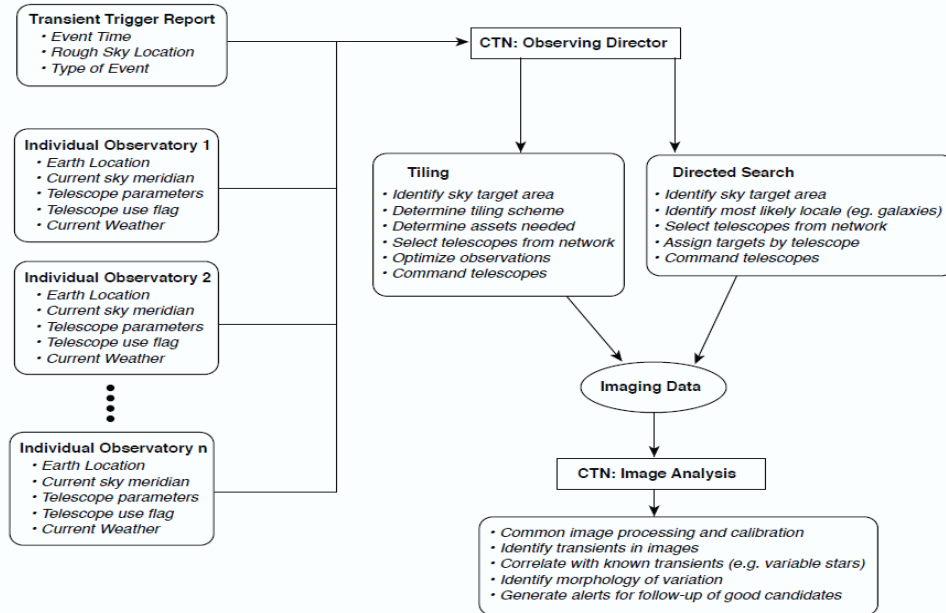


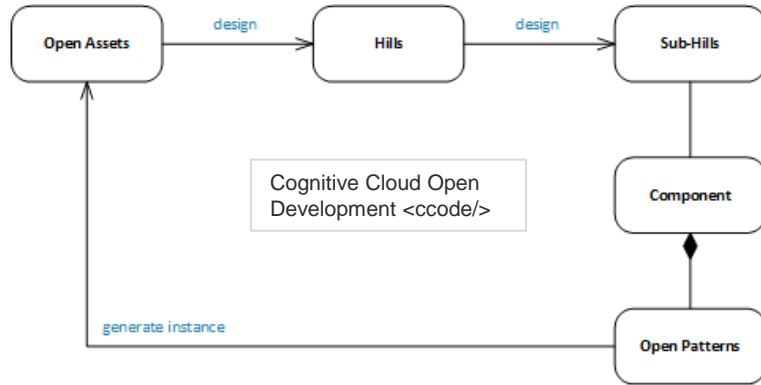
■ Solution

- **STRATEGY:** Cover the error ellipse with small aperture wide-field telescopes
- **ADVANTAGES:** Lots of glass on the sky, worldwide coverage, on demand
 - Universities, Institutes and amateurs have sub-meter telescopes as the prices of hardware has dropped over the last decade
 - Amateur astronomical groups can participate in meaningful research even with smaller telescopes
- **DISADVANTAGES:** Deep magnitudes take longer exposure times
 - Do not have a proper taxonomy yet



Predicted area for the detection of the event GW150914



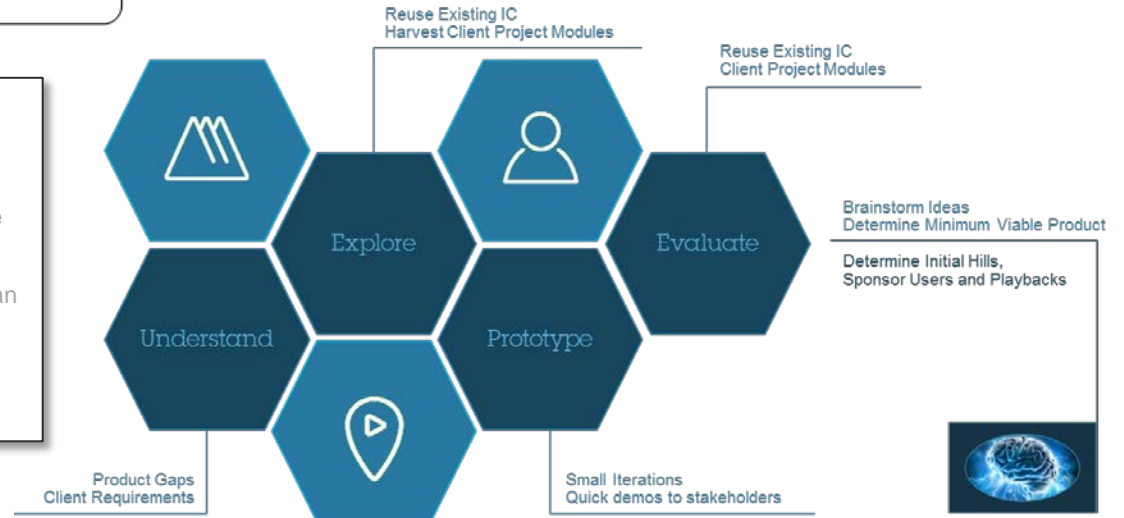


Evolving Assets using Design Thinking:

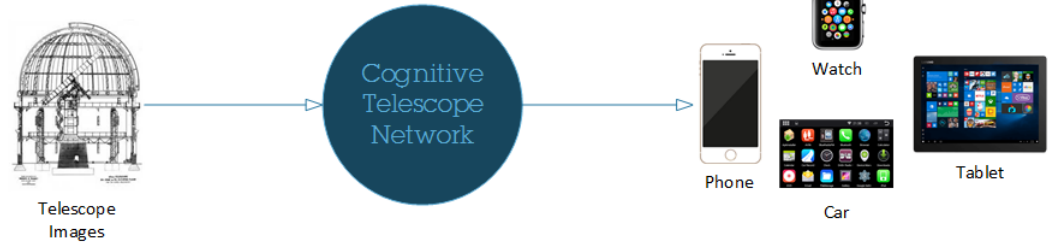
- **Open Assets**
 - ✓ Work with end users and researchers to define use cases
 - ✓ Organize thoughts under 3 Hills and Foundation
 - ✓ Define Sponsor Users for getting feedback from playbacks and continuous improvement of the design
 - ✓ Define Components / features
 - ✓ Define Open Projects, Timelines, Iterations, Playbacks, Milestones

- **Open Patterns**

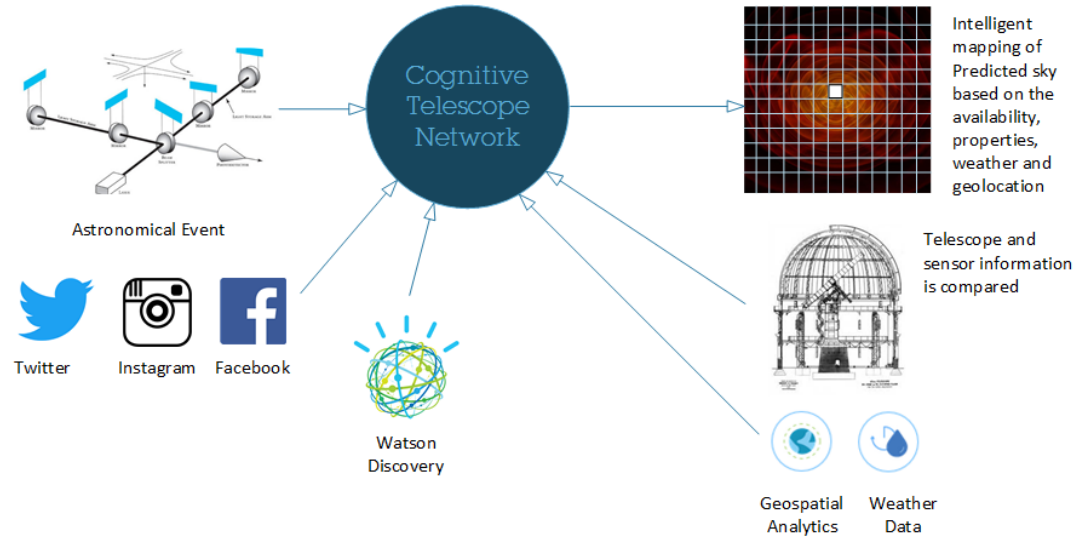
- ✓ Identify common patterns within the code and documentation from multiple assets
- ✓ Patterns may be identified and developed by the Offering Management and other teams to accelerate Open Project development
- ✓ Exemplars are patternized into templates that can generate code, document, etc. for Open Assets



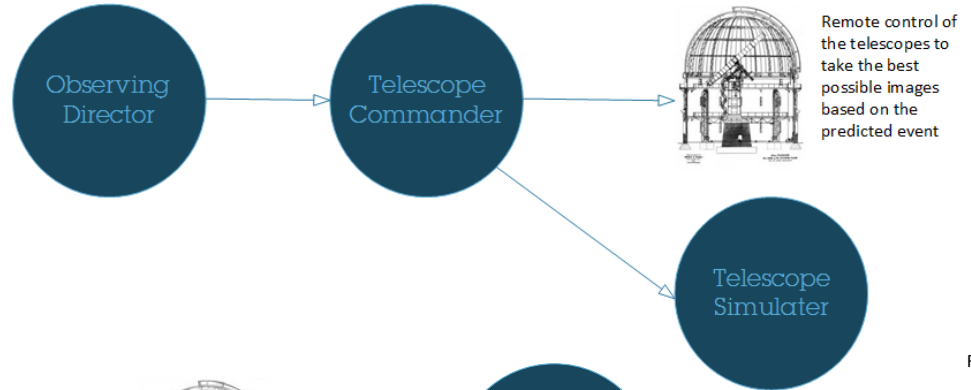
Use Case 01: Publication of Images



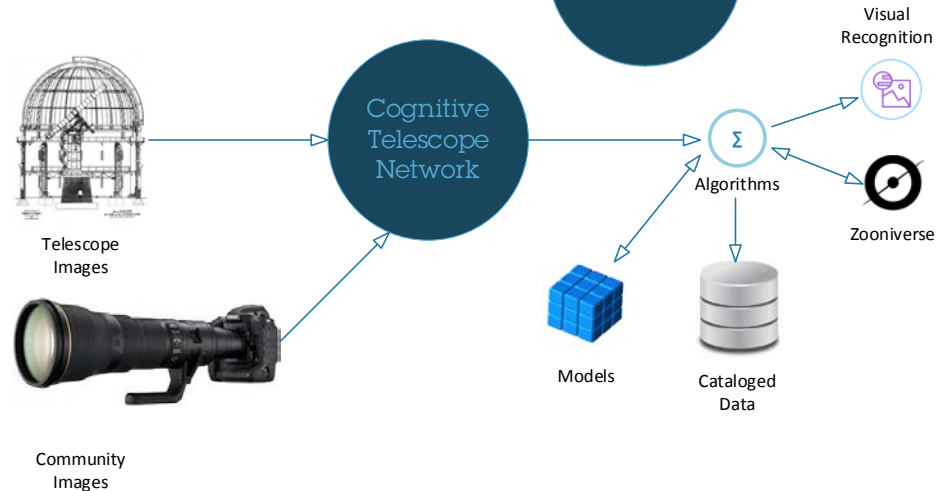
Use Case 02: Event Sourcing and Mapping of Telescopes



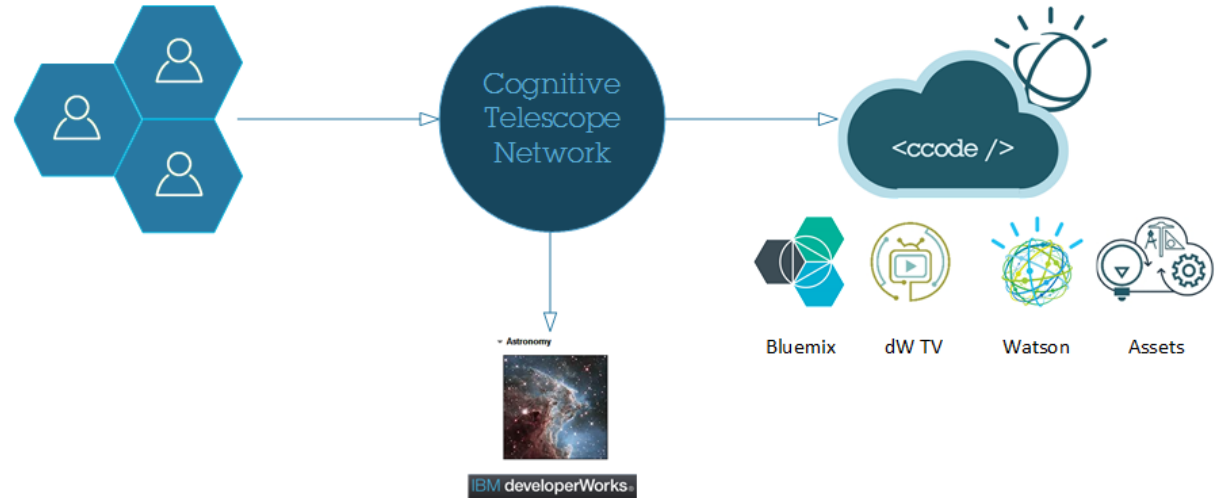
Use Case 03: Remote Control of Telescopes



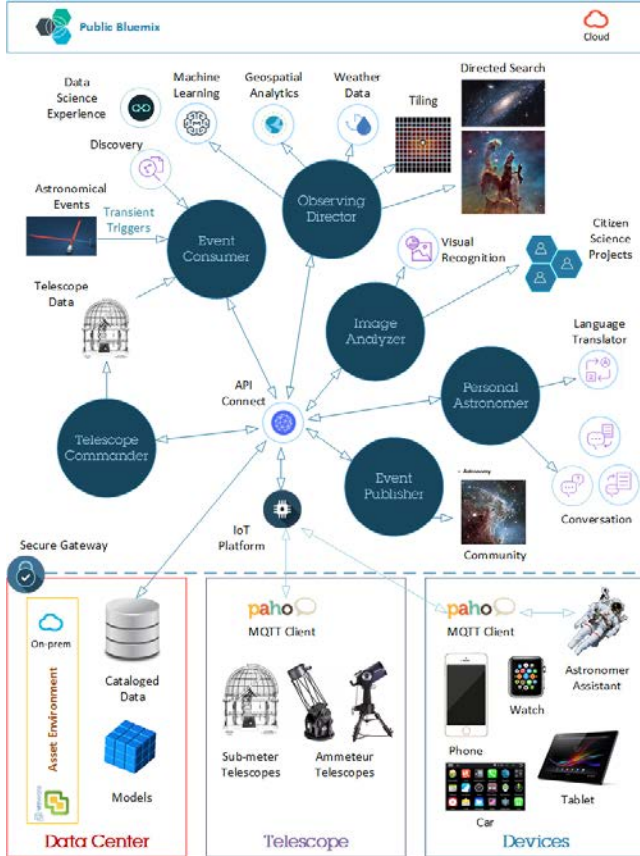
Use Case 04: Image Cataloging



Use Case 05: Building the Ecosystem



IBM Cloud Cognitive Telescopic Network



Gravitational Waves Detected 100 Years After Einstein's Prediction –

LIGO Opens New Window on the Universe with Observation of Gravitational Waves from Colliding Black Holes.

<https://www.ligo.caltech.edu/news/ligo20160211>

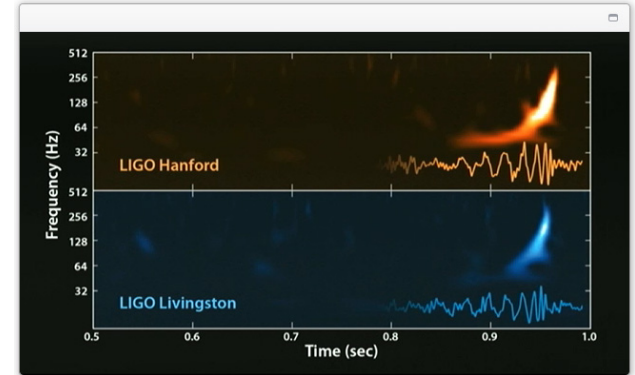
LIGO can listen to gravitational waves but cannot see the event.

- Provide identification and analysis of astronomical data from multiple sources
- Event notifications to mobile devices for building interest in the Community
- Remote control instructions to telescopes point to the specific location on the grid in the sky
- Visual Recognition integration with Zooniverse for gamification of un-identified events

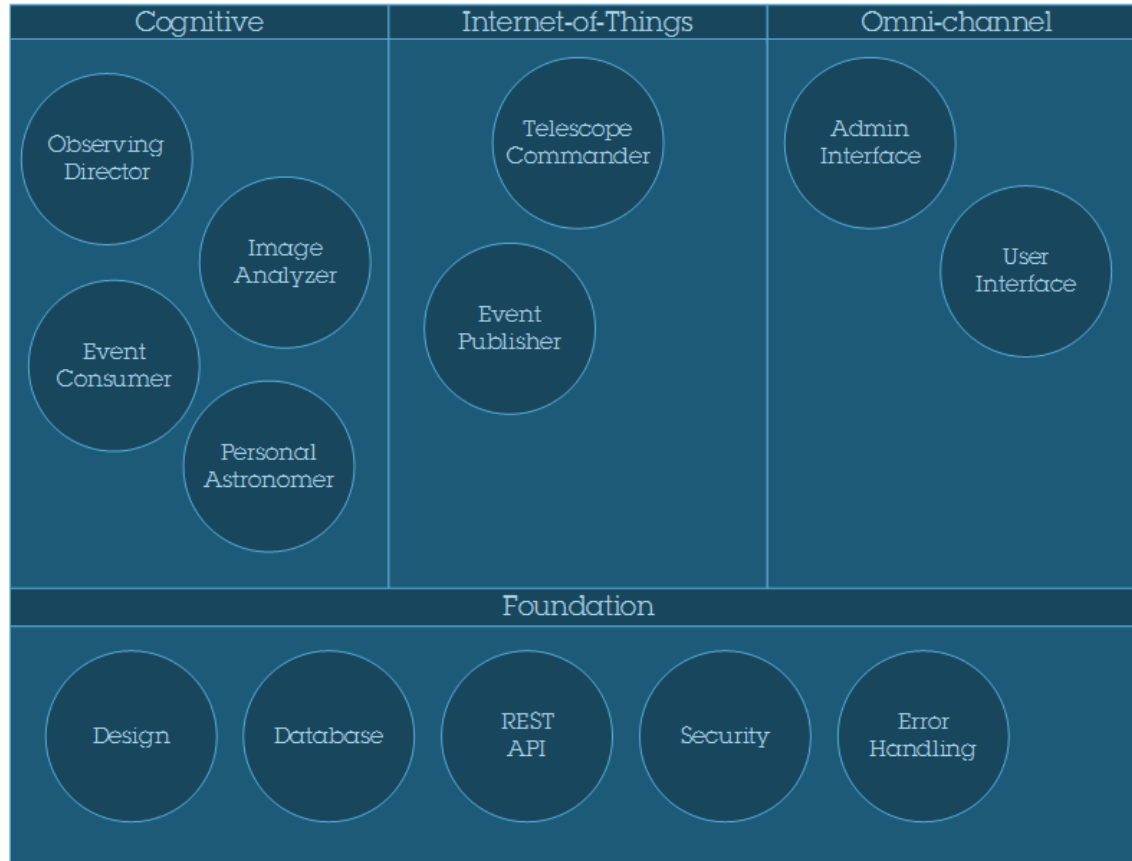
- LIGO data feed is parsed into canonical models and passed to the Event Analyzer
- If a Gravitational Wave event is detected, the available telescopes in the network are mapped into a grid to scan the sky
- Weather and Geospatial information is used to determine optimal coverage of the viewing area

Using multi-messenger astronomy – eyes and ears on the Cosmos

LIGO Update on the Search for Gravitational Waves



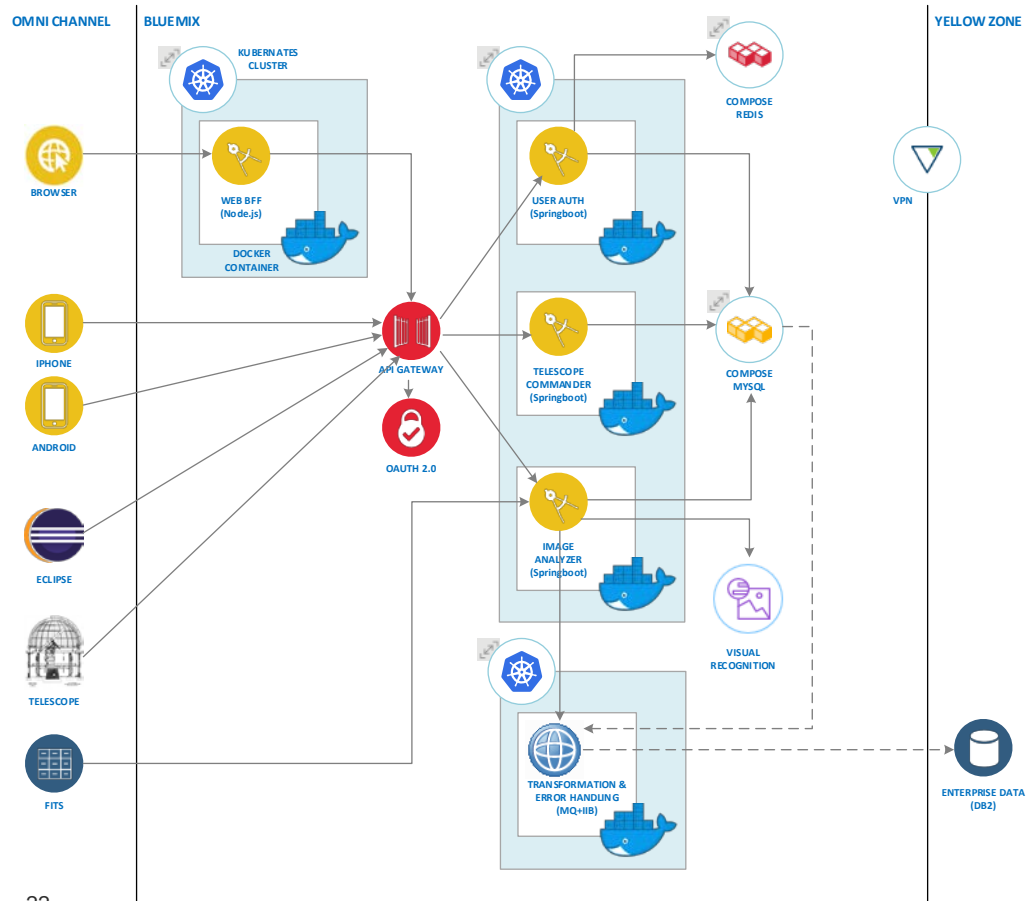
Join us: <http://ibm.biz/asset-ctn-community>



- Organize components under 3 Hills and Foundation
 - Hills are mapped to Epics
 - Sub-hills are mapped to Stories
- Cognitive
 - Components associated with Watson or Analytics services
- Internet-of-Things
 - Telescopes, sensors, mobile devices, etc. communicate over MQTT using IoT Foundation
- Omni-channel
 - User Interfaces for Web, Mobile, Telescope App and Eclipse
- Foundation
 - Database, design, API, etc.

Cognitive Telescope Network

IBM Bluemix and Watson Services brings the idea to life



API Architecture

- Based on the Reference Architecture for Blue Compute

<https://github.com/ibm-cloud-architecture/refarch-cloudnative>

Omni-channel

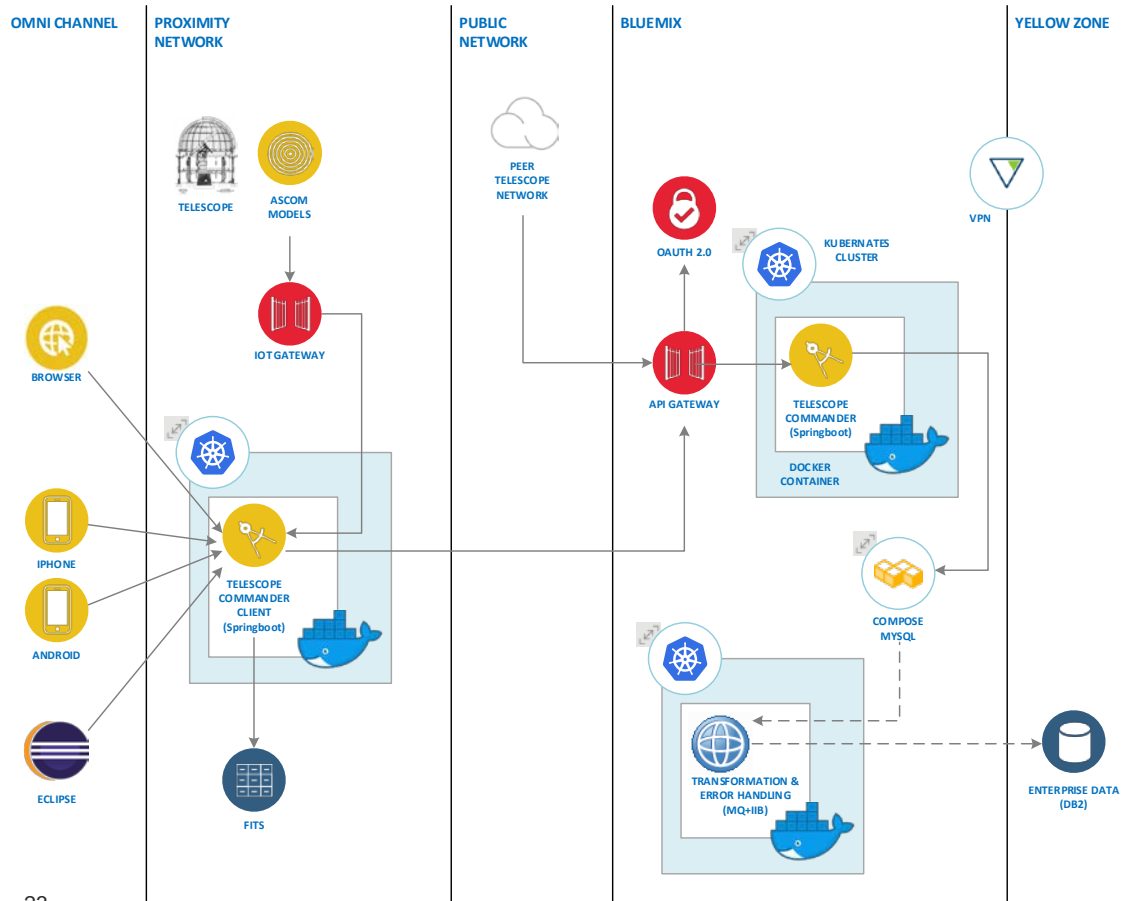
- User Interfaces for Web, Mobile, Telescope App and Eclipse

Bluemix

- Node.js implementation for Backend-for-Frontend (BFF) pattern for the web interface.
- Mobile, Eclipse, Telescope App, Web BFF communicates with API Gateway
- Authentication service provided by OAuth 2.0 provided by API Connect
- API implementations using containerized Springboot app
- Transformation and Error handling provided by containerized MQ and IBM Integration Bus (IIB)
- Compose based MySQL service for OLTP and Redis for Session caching

Yellow Zone

- Data synchronization with backend Enterprise Database using IIB flows mapping data



IoT Architecture

- Based on the Reference Architecture for IoT Reference Architecture

https://www.ibm.com/devops/method/content/architecture/iot/Architecture/0_1

Omni-channel

- User Interfaces for Web, Mobile and Eclipse

Proximity Network

- Telescope Commander client wraps the ASCOM Objects and provides an API interface
- Sensors send data using the IoT Gateway
- FITS data is saved to file system and send to the Server

Public Network

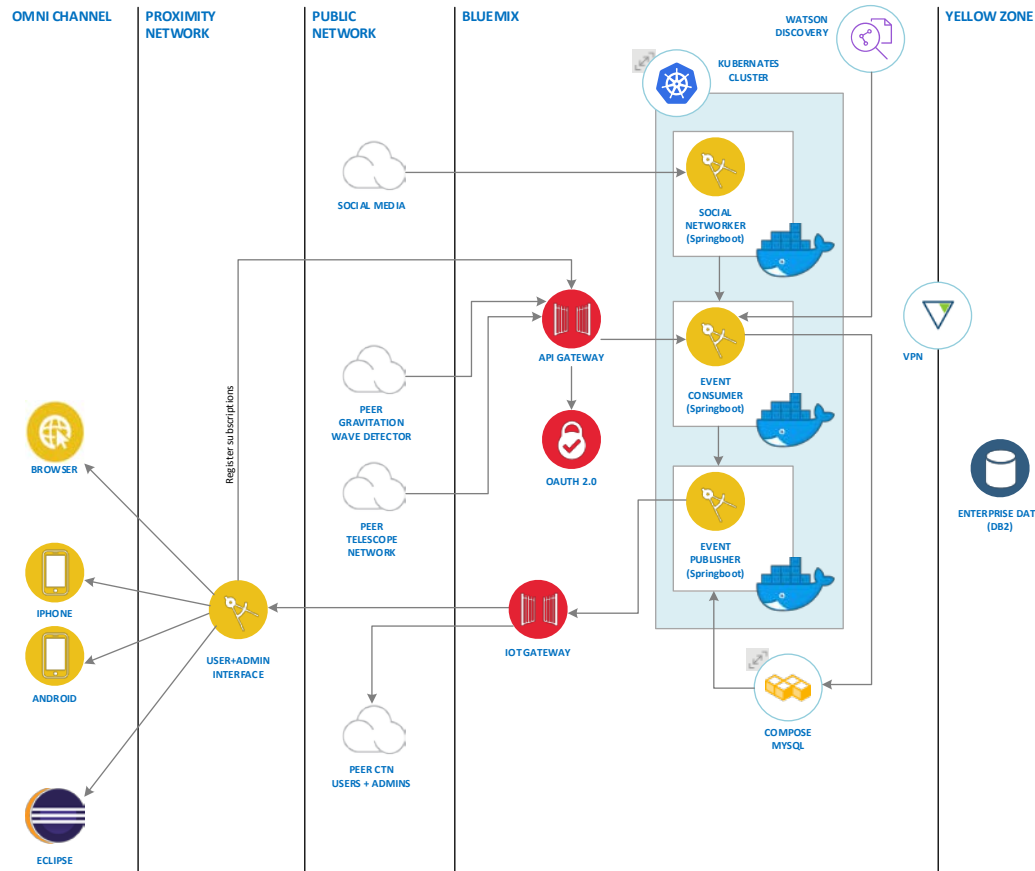
- Telescopes can register from other networks using the API for the Telescope Commander

Bluemix

- API Implementations using containerized Springboot app

Yellow Zone

- Data synchronization with backend Enterprise Database using IIB flows mapping data

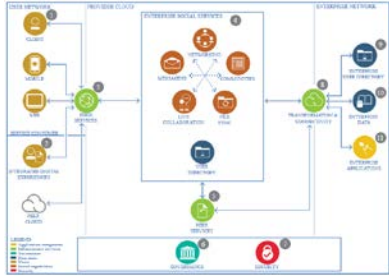


Pub/Sub Architecture

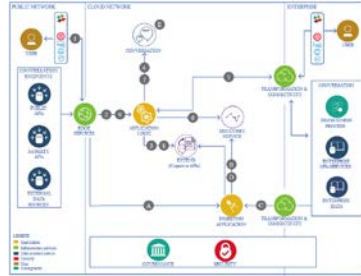
- Based on the Reference Architecture for IoT Reference Architecture
 - https://www.ibm.com/devops/method/content/architecture/iot/Architecture/0_1
- Omni-channel
 - User Interfaces for Web, Mobile and Eclipse
- Proximity Network
 - IoT Gateway hosted on Bluemix
 - App subscribes to specific events and publications
- Public Network
 - Telescopes can register from other networks using the API for the Telescope Commander
 - Social Media feeds are consumed
 - Information is published to users and administrators
- Bluemix
 - API Implementations using containerized Springboot app
 - Watson Discovery searches documents for events
- Yellow Zone
 - Data synchronization with backend Enterprise Database using IIB flows mapping data

IBM Cloud Cognitive Telescopic Network

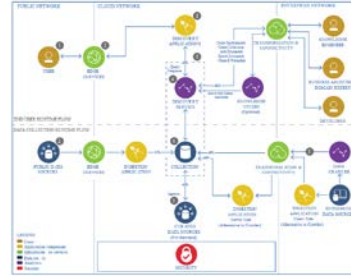
Future Architecture Alignments



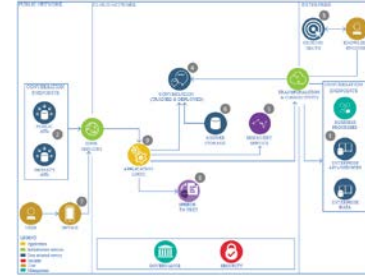
Social Reference Architecture:
https://www.ibm.com/devops/method/content/architecture/socialArchitecture/0_1



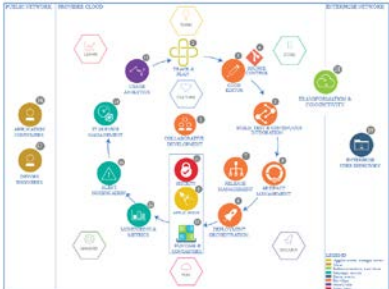
Cognitive Reference Architecture:
https://www.ibm.com/devops/method/content/architecture/cognitiveArchitecture/0_1



Discovery Reference Architecture:
<https://www.ibm.com/devops/method/content/architecture/cognitiveDiscoveryDomain/discoveryDomain>



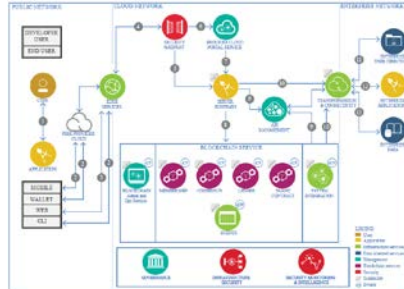
Conversation Reference Architecture:
<https://www.ibm.com/devops/method/content/architecture/cognitiveConversationDomain/discoveryDomain>



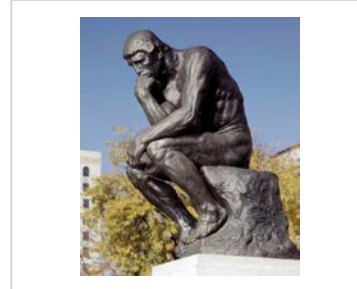
DevOps Reference Architecture:
https://www.ibm.com/devops/method/content/architecture/devOpsArchitecture/0_1



E-Commerce Reference Architecture:
https://www.ibm.com/devops/method/content/architecture/eCommerceArchitecture/0_1



Blockchain Reference Architecture:
https://www.ibm.com/devops/method/content/architecture/blockchainArchitecture/0_1



Future Reference Architecture

Gateway



DataPower

- Appliance
- Virtual Appliance (OVA)
- Docker Container
- SoftLayer, Bluemix*
- Amazon, Azure



Micro Gateway

- npm install

Runtimes

Web Server

- zip package
- Docker

Node.js

- npn install
- Docker
- Bluemix

Liberty

- zip package
- Docker
- Bluemix

Management



API Manager Cloud Manager

- Virtual Appliance (OVA)
- Docker Container
- Bluemix



Collective Controller

- npm install
- {Deprecated: 5.0.7}**



Developer Portal

- Virtual Appliance (OVA)
- Bluemix



Kubernetes Cluster

- Bluemix



Docker Swarm

Development

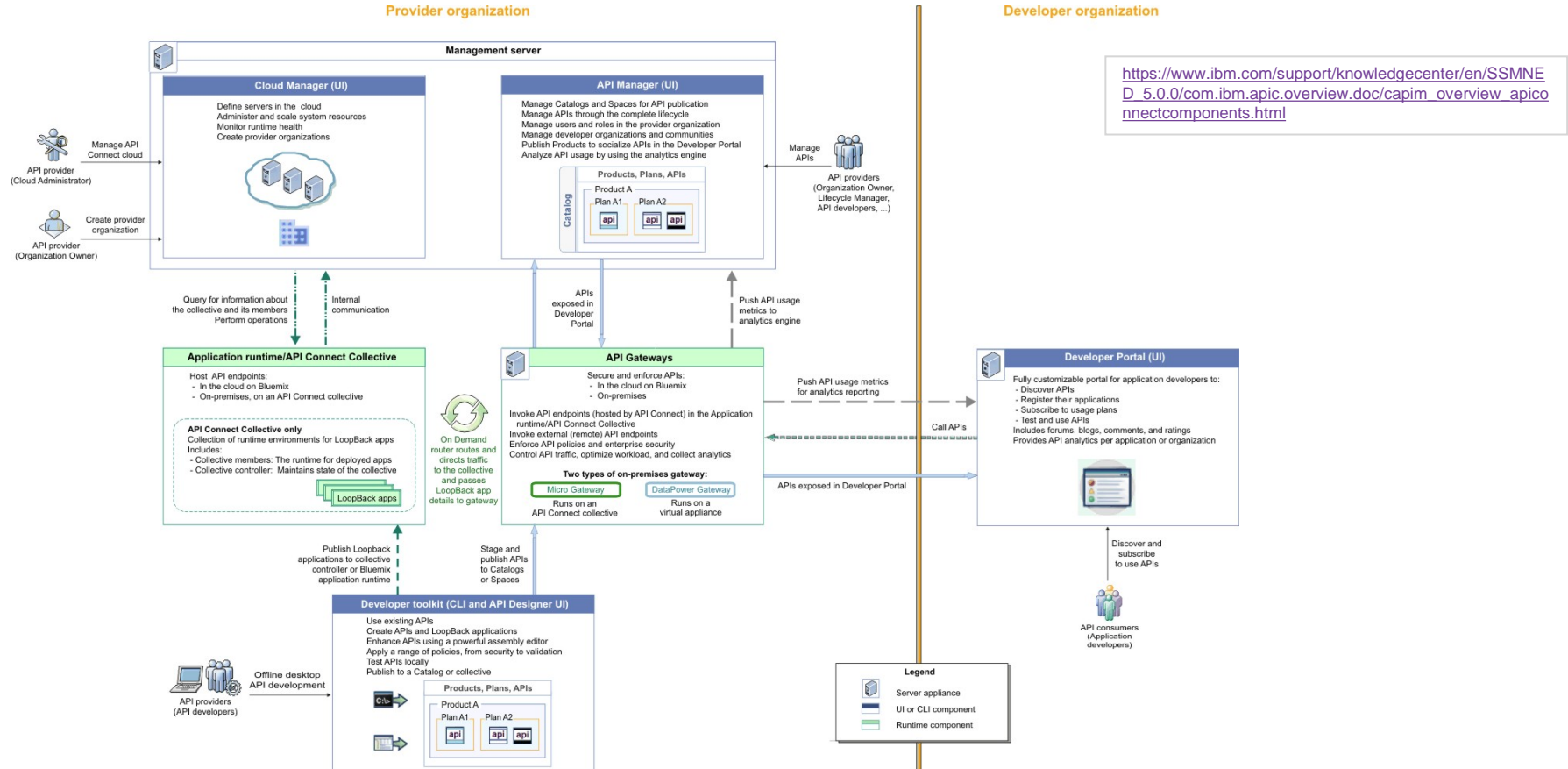


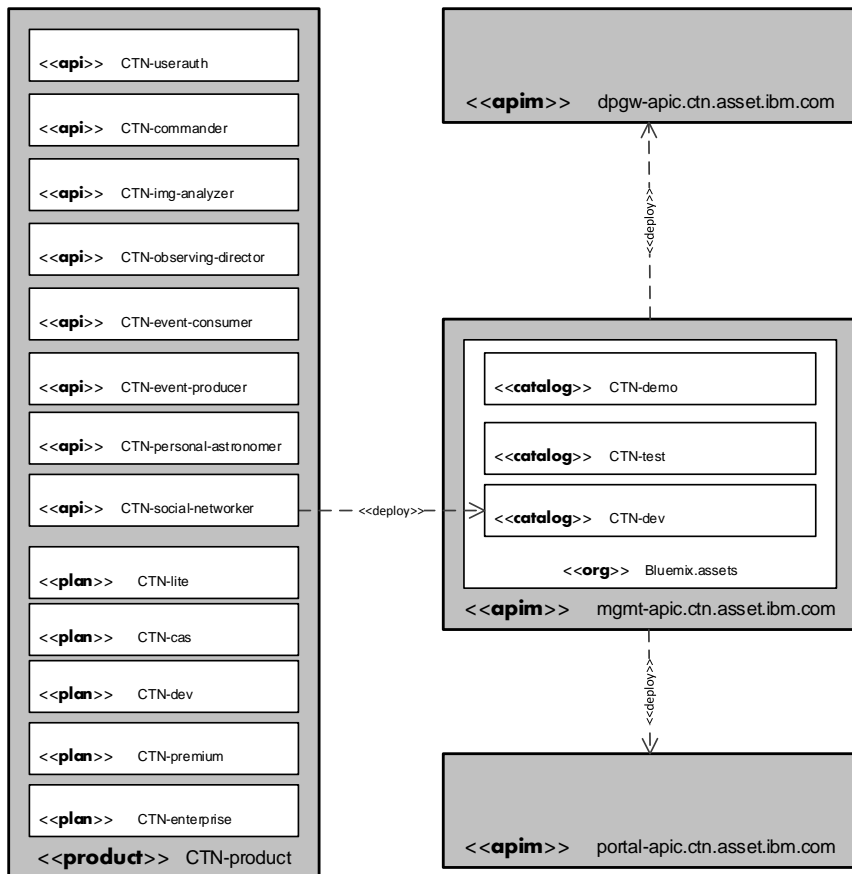
APIC Toolkit

- npm install

N.B.:

- **OVA:** VMWare/Xen hypervisors
- **Bluemix:** *Uses DataPower Gateway but is not exposed to developer





API Definitions

- The User Authentication API provides the login and authorization and creates a persistent session
- All other APIs are dependent on the login to be successful and validated
- Component specific APIs

Product Definition

- APIs are packaged in the CTN-product
- Several Plans are added to the product for rate limits and conditions and prices for the plan

Catalog

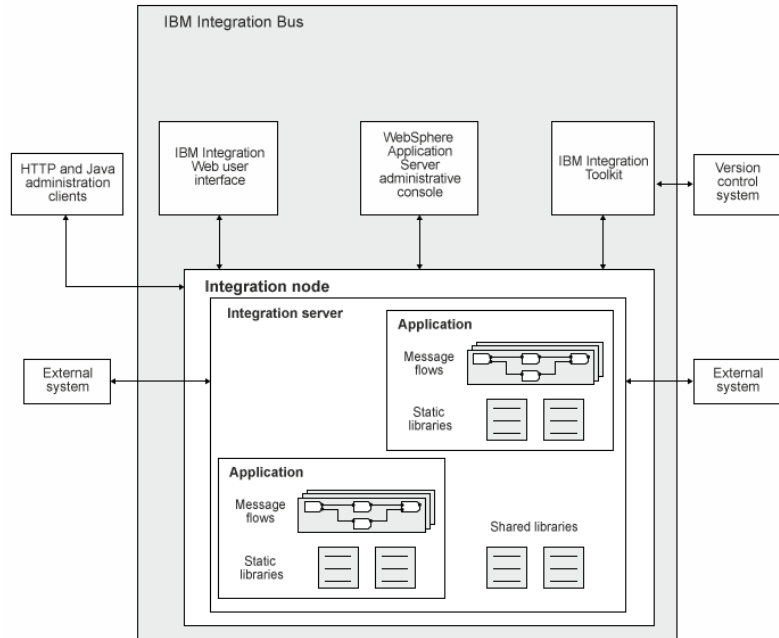
- Products are deployed to a catalog in an API manager organization

Gateway

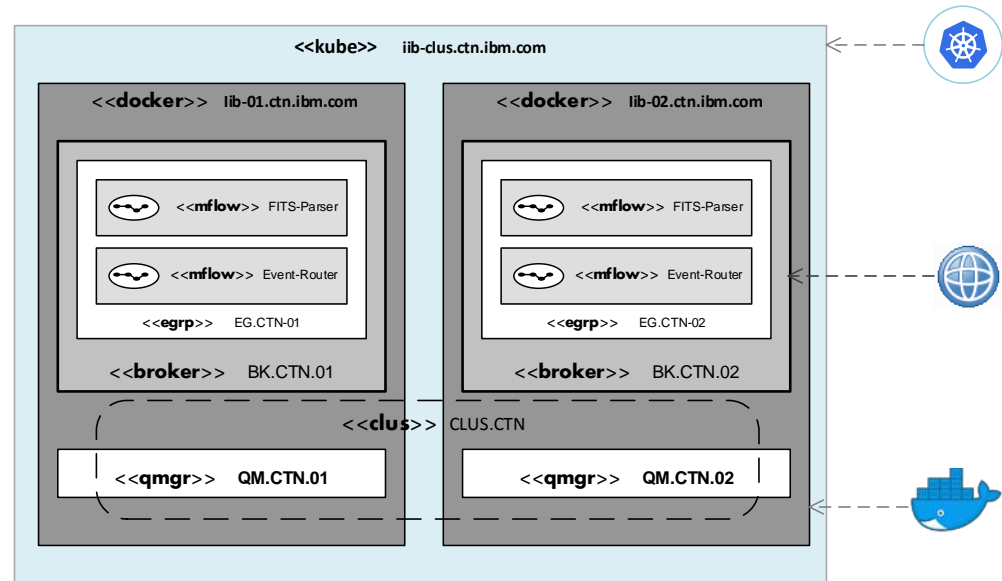
- Datpower Gateway hosts the API definition and a Security enforcement point

Developer Portal

- Provides an interface to track and subscribe to published APIs
- Analytics to determine the usage



https://www.ibm.com/support/knowledgecenter/en/SSMKHH_10.0.0/com.ibm.etools.mft.doc/ab20551_.htm



673nmos.fits - ESA/ESO/NASA FITS Liberator 3

Processing Metadata Image Headers Help Guide

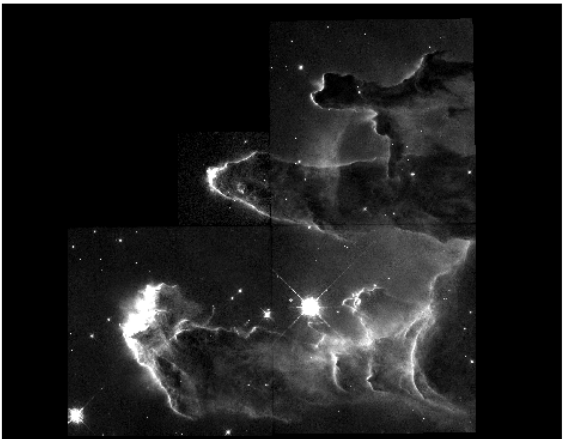


Image data

Image 1, Plane 1

X 769 px RA 4.72 Input 8.47
Y 141 px DEC 3.82 Stretched 8.47

Width 1600 px Height 1600 px

Image statistics

	Input	Stretched
Min	-15.08	-15.08
Max	3363.96	3363.96
Mean	8.45	8.45
Median	7.40	7.40
StdDev	27.78	27.78

Scaling and stretch (Advanced)

Stretch function Linear

Background level 0.00

Peak level 38.36

Scaled peak level 10.00

Auto scaling Apply values

Channels

8-bit
16-bit
32-bit

Undefined


Black
Transparent

Open File
Save File
Save & Edit
Options
About
Reset

Preview
Flip Image
Freeze settings

Mark in preview
Undefined (red)
White clipping (green)
Black clipping (blue)

Show image information for:
Scaled
Stretched



Content

- Title
- Headline
- Description
- Subject Category
- Subject Name
- Distance
- Distance Notes
- ReferenceURL
- Credit
- Date
- ID
- Type
- Image Product Quality

Observation

- Facility
- Instrument
- Spectral Color Assignment
- Spectral Band
- Spectral Bandpass
- Spectral Central Wavelength
- Spectral Notes
- Temporal StartTime
- Temporal Integration Time
- Duration

Coordinate

- Spatial Coordinate Frame
- Spatial Equinox
- Spatial Reference Value
- Spatial Reference Dimension

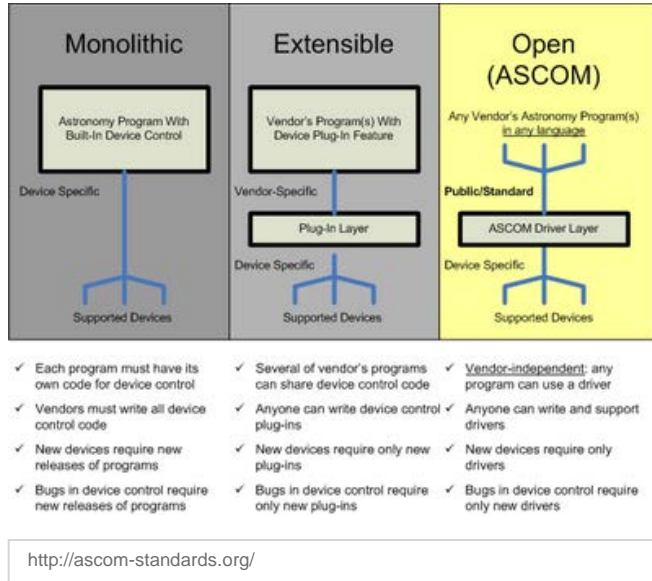
Image #1

```

SIMPLE = T / FITS STANDARD
BITPIX = -32 / FITS BITS/PIXEL
NAXIS = 2 / NUMBER OF AXES
NAXIS1 = 1600 /
NAXIS2 = 1600 /
EXTEND = T / There maybe standard extensions
BSCALE = 1.0E0 / REAL = TAPE*BSCALE + BZERO
BZERO = 0.0E0 /
ORIGIN = 2112 / PSIIK of original image
ORIGIN = 'STIS1-STSDAS' / Fitsio version 21-SEP-1996
FITSDATE = '2005-07-01' / Date FITS file was created
FILENAME = '673nmos_ovr.hhh' / Original filename
ALLG-MAX = 0.000000E0 / Data max in all groups
ALLG-MIN = 0.000000E0 / Data min in all groups
DATATYPE = 'FLOATING' / Original datatype: Single precision real
SDASMDIM = 1
CRVAL1 = 274.711522994E2 /
CRVAL2 = -15.816390682904 /
CRPIX1 = 386.5 /
CRPIX2 = 396. /
CD1_1 = 1.879013E-5 /
CD1_2 = -2.051193E-5 /
CD2_1 = -2.029358E-5 /
CD2_2 = -1.879913E-5 /
DATEMIN = 0.000000E0 / DATA MIN
DATEMAX = 0.000000E0 / DATA MAX
MIR_RECV = T
ORIENTAT = -131.9115 /
FILLCNT = 0 /
FERRCNT = 0 /
FERRTIME = 49808.7928710322 /
LFRTIME = 49808.7930388563 /
CTYPE1 = 'RA---TAN' /
    
```

<https://fits.gsfc.nasa.gov/>

FITS Liberator: https://www.spacetelescope.org/projects/fits_liberator/download_v301/



ASCOM Platform 6.3

[Download](#)

[Platform 6.3 Help \(online\)](#)

Required for all drivers (see notes for [Windows 7](#) and [Windows XP!](#)). This will install the Platform on a new PC, and it will also upgrade earlier installations of Platform versions 4, 5, and 6.

Drivers & Plug-ins

[Go to Page](#)

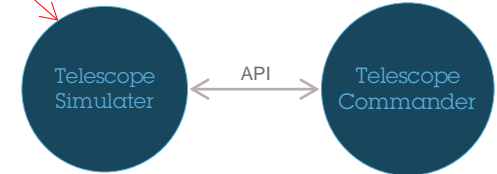
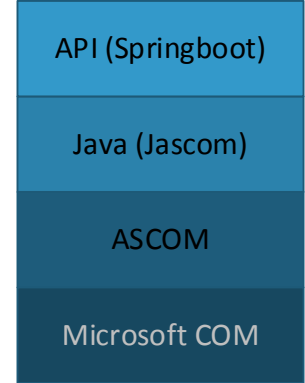
Download and install the driver(s) for your astronomy instruments and devices. You'll also find plug-ins for TheSky and other useful tools and components here for download.

- ASCOM Platform 6
 - ASCOM Compatible Software
 - ASCOM Drivers and Downloads
 - ASCOM User Guide
 - Check for Updates
 - Help and Device Interface Standards
 - How to get support
 - Show Platform Version
 - Developer Documentation
 - Developer Tools
 - Scope-Dome Hubs
- Simulators
 - Dome Simulator
 - FilterWheel Simulator .NET
 - FilterWheel Simulator
 - Focus Simulator
 - Rotator Simulator .NET
 - Switch Simulator
 - Telescope Simulator .NET
 - Telescope Simulator
- Tools

Profile Explorer 6.2.0.0

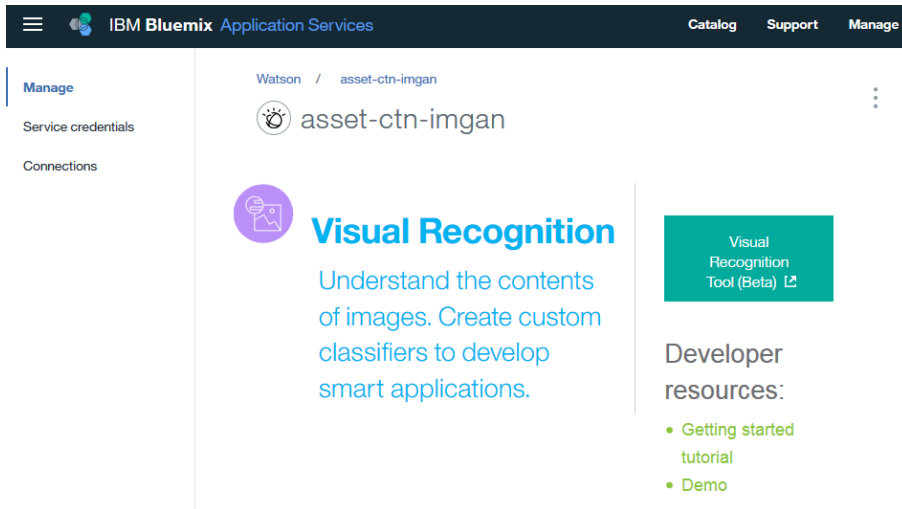
File Options Help

- Profile Root
 - Astrometry
 - Camera Drivers
 - Chooser
 - COMPortSettings
 - Dome Drivers
 - FilterWheel Drivers
 - Focuser Drivers
 - ForcePlatformVersion
 - ForcePlatformVersionSeparator
 - ForceSystemTimer
 - ObservingConditions Drivers
 - Platform
 - Rotator Drivers
 - SafetyMonitor Drivers
 - Switch Drivers
 - Telescope Drivers
 - Video Drivers



CTN Models (ASCOM):

Telescope	Focuser
Mount	Rotator
Dome	WeatherSensor
Camera	SafetyMonitor
FilterWheel	PowerSwitch



The screenshot shows the IBM Bluemix Application Services console. The top navigation bar includes 'IBM Bluemix Application Services', 'Catalog', 'Support', and 'Manage'. The left sidebar has 'Manage', 'Service credentials', and 'Connections'. The main content area shows the service 'asset-ctn-imag' with a 'Visual Recognition' card. The card includes a description: 'Understand the contents of images. Create custom classifiers to develop smart applications.' and a 'Developer resources' section with links for 'Getting started tutorial' and 'Demo'. A 'Visual Recognition Tool (Beta)' button is also visible.

<https://console.bluemix.net/docs/services/visual-recognition/getting-started.html#getting-started-tutorial>

<https://console.bluemix.net/docs/services/visual-recognition/tutorial-custom-classifier.html#creating-a-custom-classifier>

```
curl -X POST \ --form "beagle_positive_examples=@beagle.zip" \ --form "husky_positive_examples=@husky.zip" \ --form "goldenretriever_positive_examples=@golden-retriever.zip" \ --form "negative_examples=@cats.zip" \ --form "name=dogs" \ "https://gateway-a.watsonplatform.net/visual-recognition/api/v3/classifiers?api_key={api-key}&version=2016-05-20"
```

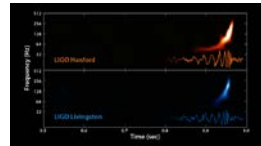
- Step 1: Copy your credentials
- Step 2: Creating a custom classifier
- Step 3: Updating an existing custom classifier
- Step 4: Classifying an image with a custom classifier

Send images to Watson Visual Recognition
If the score is lower than the threshold for the assigned class send image to the Zooniverse project for crowd sourcing
Randomized tests to determine confidence level



- Step 1: Train Watson with Astronomy Pictures
- Step 2: Classify Objects – planets, stars, galaxies, nebula
- Step 3: Compare with known discovered objects
- Step 4: Mark unidentified objects for scientific investigation
- Step 5: Learn from the scientists

- Step 1: Train Watson with LIGO event data
- Step 2: Eliminate noise from the data
- Step 3: Detect events and instruction Observing Director
- Step 4: Learn from false identification of events



LIGO event data

Name	Telescopes	Size	Science goals	Website
HATnet ^a	7	20cm f/1.8	Exoplanet Discovery	https://hatnet.org
Catalina Sky Survey ^b	3	1.5m f/1.6 1.0m f/2.6 0.7m f/1.8	Near Earth Asteroid Discovery	https://catalina.lpl.arizona.edu
MINERVA ^c	4	0.7m f/6.5	Exoplanet Radial Velocity	https://www.cfa.harvard.edu/minerva/
AAVSONet ^d	~12		Proposal based science	https://www.aavso.org/aavsonet
GTN ^e			Gamma-ray Burst	http://gtn.sonoma.edu/
SkyNet ^f	10	0.4 – 1 m	Proposal based science	https://skynet.unc.edu/
LCO ^g	17	1-2 m	Proposal based science	https://lco.global/

a Hungarian-made Automated Telescope Network at Princeton University

b Catalina Sky Survey at University of Arizona

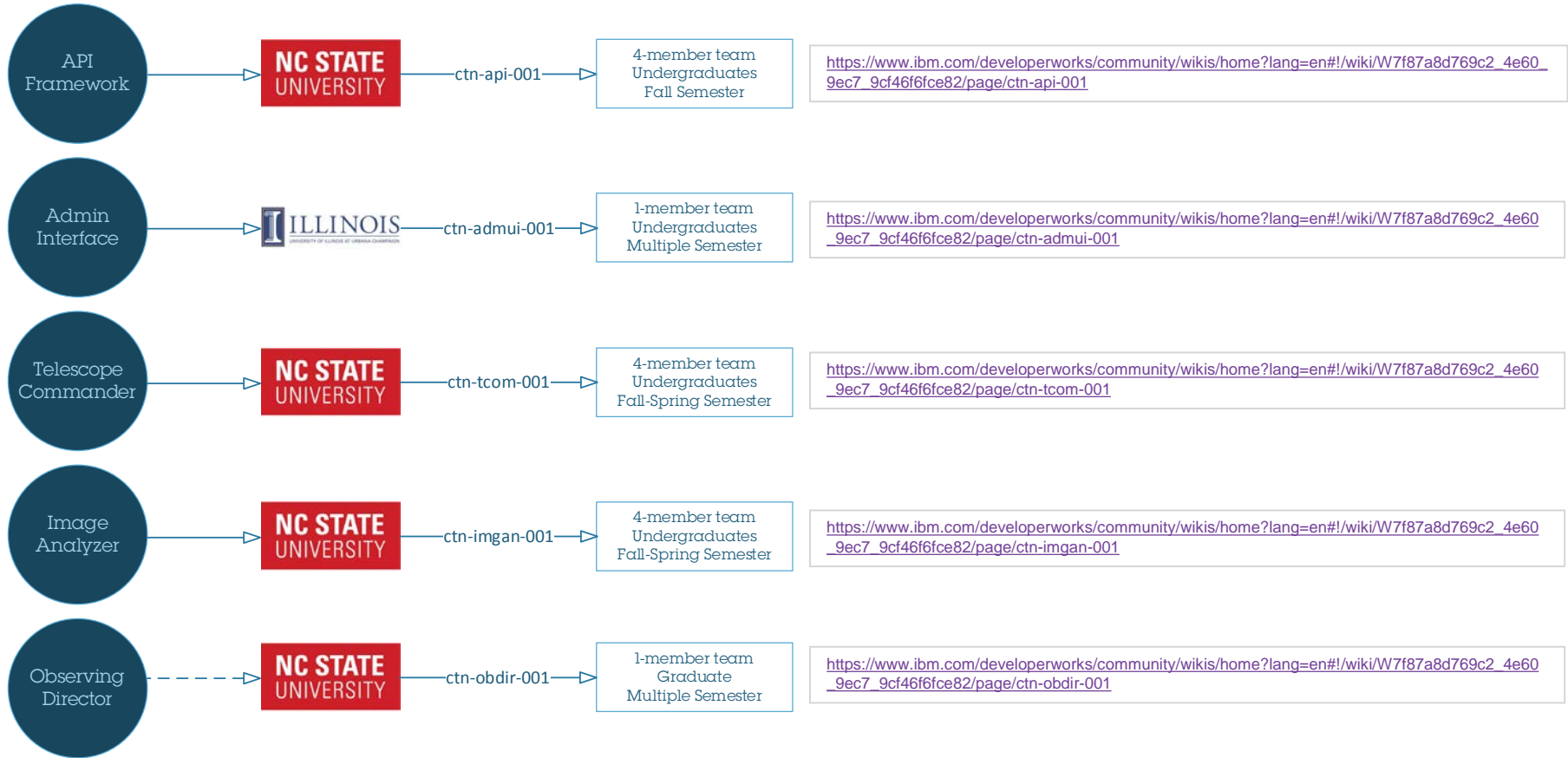
c MINIature Exoplanet Radial Velocity Array at Harvard-Smithsonian, Penn State, University of Montana, University of New South Wales

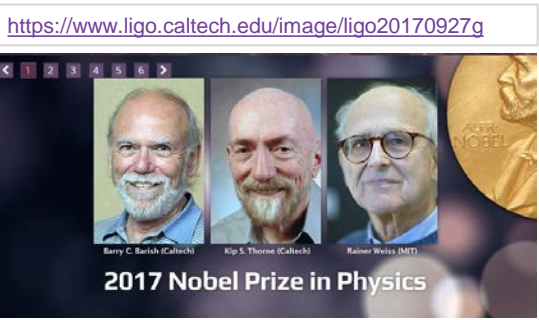
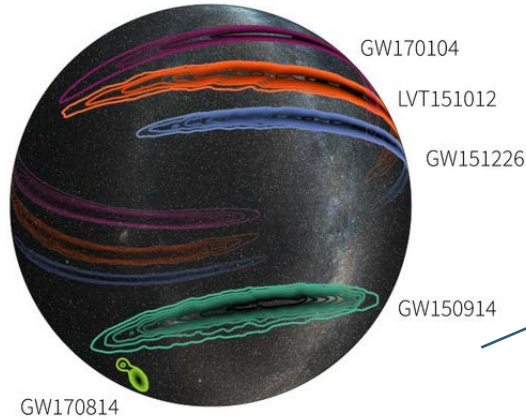
d American Association of Variable Star Observers at Multiple Institutes World Wide

e Global Telescope Network at Sonoma State University

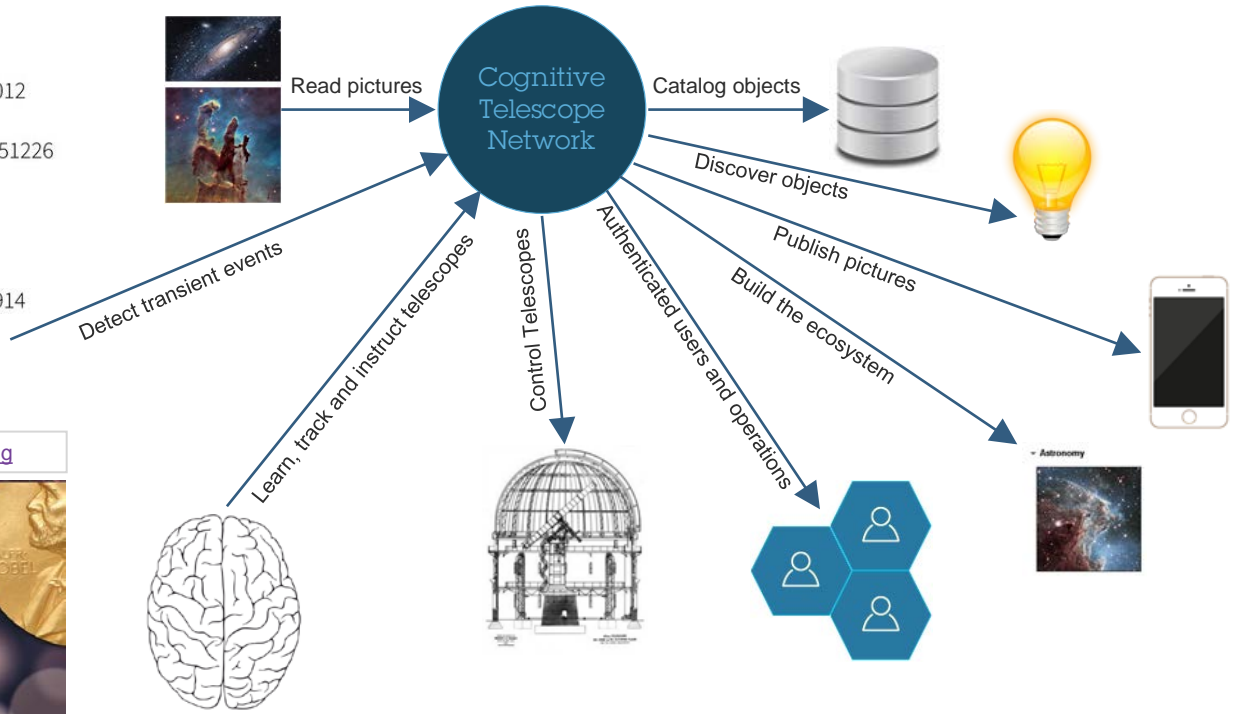
f SkyNet Robotic Telescope Network at University of North Carolina at Chapel Hill

g Las Cumbres Observatory, a Non-Profit Organization





Nobel Prize awarded to LIGO Founders, October 3, 2017: 2017 Nobel Prize in Physics: **Barry Barish** and **Kip Thorne** of Caltech and **Rainer Weiss** of MIT



“Imagination is more important than Knowledge.”

- Albert Einstein

It's not just about building a cloud infrastructure – it's about strategically adopting cloud to realize its benefits

3 practices

IBM Bluemix Garage

Services immersed in startup DNA and the newest technologies

Cloud Advisory Services and integrated solutions for hybrid cloud

IBM Cloud Professional Services

IBM Analytics Services

Analytics-based solutions that empower your data

5 principles

- 1. METHODOLOGY & ASSETS**
We provide the most potent hybrid cloud methodology and assets available.
- 2. DEEP SKILLS**
We curate the most agile, deeply-skilled expert teams in the industry.
- 3. FAST SUCCESS**
We champion prescriptive, guided cloud adoption journeys with adaptable blueprints.
- 4. CONFIDENCE**
We enable transformations by empowering our clients.
- 5. WORLD-CLASS SUPPORT**
We deliver world-class support to make sure you succeed.

Countless capabilities



Stop by the Services Booth in the expo to talk about how we can help

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